

Parallel Search for Maximum Satisfiability

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What is Boolean Satisfiability?

CNF Formula:

$$\begin{array}{ccc} \bar{x}_2 \vee \bar{x}_1 & x_2 \vee \bar{x}_3 & x_1 \\ x_3 & x_2 \vee \bar{x}_1 & \bar{x}_3 \vee x_1 \end{array}$$

- Boolean Satisfiability (SAT):
 - Decide if the formula is satisfiable or unsatisfiable

What is Boolean Satisfiability?

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- Formula is unsatisfiable

What is Boolean Satisfiability?

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- Formula is unsatisfiable
- How many clauses can we satisfy?

What is Maximum Satisfiability?

CNF Formula:

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- Maximum Satisfiability (MaxSAT):
 - Find an assignment that maximizes (minimizes) number of satisfied (unsatisfied) clauses

What is Maximum Satisfiability?

CNF Formula:

$\bar{x}_2 \vee \bar{x}_1$	$x_2 \vee \bar{x}_3$	x_1
x_3	$x_2 \vee \bar{x}_1$	$\bar{x}_3 \vee x_1$

- An optimal solution would be:
 - $\nu = \{x_1 = 1, x_2 = 1, x_3 = 1\}$
- This assignment unsatisfies only 1 clause

MaxSAT Problems

- MaxSAT:
 - All clauses are soft
 - Minimize number of unsatisfied soft clauses
- Partial MaxSAT:
 - Clauses are soft or hard
 - Hard clauses must be satisfied
 - Minimize number of unsatisfied soft clauses
- Weighted Partial MaxSAT:
 - Clauses are soft or hard
 - Weights associated with soft clauses
 - Minimize sum of weights of unsatisfied soft clauses

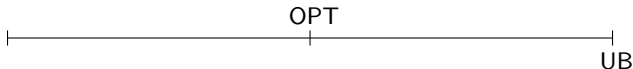
Why is MaxSAT Important?

- Many real-world applications can be encoded to MaxSAT:
 - Software package upgradeability:
 - Eclipse platform uses MaxSAT for managing the plugins dependencies
 - Error localization in C code
 - Debugging of hardware designs
 - Haplotyping with pedigrees
 - Reasoning over Biological Networks
 - Course timetabling
 - Combinatorial auctions
 - ...
- MaxSAT algorithms are effective for solving real-world problems

Outline

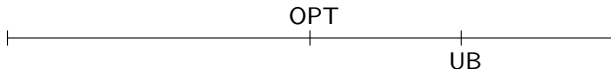
- MaxSAT Algorithms:
 - Linear search algorithms
 - Unsatisfiability-based algorithms
- Parallel MaxSAT:
 - Parallel algorithms
 - Deterministic approaches
 - Clause sharing heuristics
- Sequential MaxSAT:
 - Partitioning-based algorithms

Linear Search Algorithms



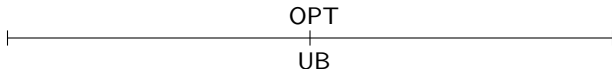
- Optimum solution (OPT):
 - Assignment with **minimum** cost
- Upper Bound (UB) value:
 - Cost **greater than or equal** to OPT
- Linear search algorithms:
 - Refine UB value until OPT is found

Linear Search Algorithms



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Linear Search Algorithms

Partial MaxSAT Formula:

$$\varphi_h \text{ (Hard):} \quad \bar{x}_2 \vee \bar{x}_1 \quad x_2 \vee \bar{x}_3$$

$$\varphi_s \text{ (Soft):} \quad x_1 \quad x_3 \quad x_2 \vee \bar{x}_1 \quad \bar{x}_3 \vee x_1$$

Linear Search Algorithms

Partial MaxSAT Formula:

$$\varphi_h : \quad \bar{x}_2 \vee \bar{x}_1 \quad x_2 \vee \bar{x}_3$$

$$\varphi_s : \quad x_1 \vee r_1 \quad x_3 \vee r_2 \quad x_2 \vee \bar{x}_1 \vee r_3 \quad \bar{x}_3 \vee x_1 \vee r_4$$

- Relax all soft clauses
- Relaxation variables:
 - $V_R = \{r_1, r_2, r_3, r_4\}$
 - If a soft clause ω_i is **unsatisfied**, then $r_i = 1$
 - If a soft clause ω_i is **satisfied**, then $r_i = 0$

Linear Search Algorithms

Partial MaxSAT Formula:

$\varphi_h :$

$$\bar{x}_2 \vee \bar{x}_1$$

$$x_2 \vee \bar{x}_3$$

$\varphi_s :$

$$x_1 \vee r_1$$

$$x_3 \vee r_2$$

$$x_2 \vee \bar{x}_1 \vee r_3$$

$$\bar{x}_3 \vee x_1 \vee r_4$$

$$V_R = \{r_1, r_2, r_3, r_4\}$$

- Formula is satisfiable
 - $\nu = \{x_1 = 1, x_2 = 0, x_3 = 0, r_1 = 0, r_2 = 1, r_3 = 1, r_4 = 0\}$
- **Goal:** Minimize the number of relaxation variables assigned to 1

Linear Search Algorithms

Partial MaxSAT Formula:

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$x_2 \vee \bar{x}_3$

$\varphi_s :$

$x_1 \vee r_1$

$x_3 \vee r_2$

$x_2 \vee \bar{x}_1 \vee r_3$

$\bar{x}_3 \vee x_1 \vee r_4$

$$\mu = 2 \quad V_R = \{r_1, r_2, r_3, r_4\}$$

- r_2 and r_3 were assigned truth value 1:
 - Current solution unsatisfies 2 soft clauses
- Can less than 2 soft clauses be unsatisfied?

Linear Search Algorithms

Partial MaxSAT Formula:

$$\varphi_h : \quad \bar{x}_2 \vee \bar{x}_1 \quad x_2 \vee \bar{x}_3 \quad \text{CNF}(\sum_{r_i \in V_R} r_i \leq 1)$$

$$\varphi_s : \quad x_1 \vee r_1 \quad x_3 \vee r_2 \quad x_2 \vee \bar{x}_1 \vee r_3 \quad \bar{x}_3 \vee x_1 \vee r_4$$

$$\mu = 2 \quad V_R = \{r_1, r_2, r_3, r_4\}$$

- Add cardinality constraint to refine UB value:
 - $\text{CNF}(r_1 + r_2 + r_3 + r_4 \leq 1)$

Linear Search Algorithms

Partial MaxSAT Formula:

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- Formula is unsatisfiable:
 - There are no solutions that unsatisfy 1 or less soft clauses

Linear Search Algorithms

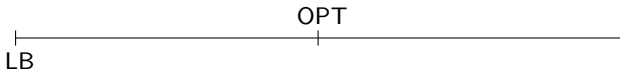
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φ_s :	x_1	x_3	$x_2 \vee \bar{x}_1$	$\bar{x}_3 \vee x_1$

$$\mu = 2 \quad V_R = \{r_1, r_2, r_3, r_4\}$$

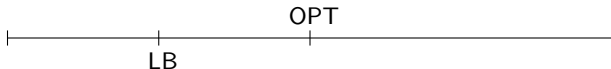
- **Optimal solution:**
 - $\nu = \{x_1 = 1, x_2 = 0, x_3 = 0\}$

Unsatisfiability-based Algorithms



- Lower Bound (LB) value:
 - Cost **smaller than or equal** to OPT
- Unsatisfiability-based algorithms:
 - Use unsatisfiable cores to refine LB value until OPT is found

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- Formula is unsatisfiable
- Identify an unsatisfiable core

Unsatisfiability-based Algorithms

Partial MaxSAT Formula:

$$\varphi_h: \quad \bar{x}_2 \vee \bar{x}_1 \quad x_2 \vee \bar{x}_3$$

$$\text{CNF}(r_1 + r_2 \leq 1)$$

$$\varphi_s: \quad x_1 \vee r_1 \quad x_3 \vee r_2 \quad x_2 \vee \bar{x}_1 \quad \bar{x}_3 \vee x_1$$

- Relax unsatisfiable core:
 - Add relaxation variables
 - Add at-most-one constraint

Unsatisfiability-based Algorithms

Partial MaxSAT Formula:

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 - $\nu = \{x_1 = 1, x_2 = 0, x_3 = 0\}$

Outline

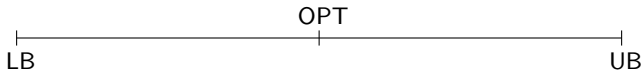
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- Parallel MaxSAT:
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- Sequential MaxSAT:
 - Partitioning-based algorithms

Why Parallel MaxSAT?

- Multicore processors are now predominant
- Several parallel SAT solvers have emerged:
 - Search space splitting
 - Portfolio
- Parallel approaches for MaxSAT are just starting
- This thesis presents the **first** parallel MaxSAT algorithms

Parallel MaxSAT (2 threads)

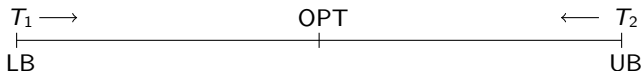
[RCRA'11, AI Comm.'12]



- Linear search algorithms:
 - UB search
- Unsatisfiability-based algorithms:
 - LB search

Parallel MaxSAT (2 threads)

[RCRA'11, AI Comm.'12]



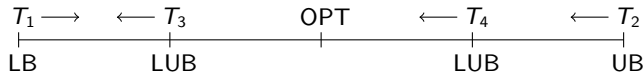
- Linear search algorithms:
 - UB search
- Unsatisfiability-based algorithms:
 - LB search
- Parallel search:
 - Search on LB and UB of the optimal solution
 - Exchange information

Parallel MaxSAT (n threads) [RCRA'11, ICTAI'11, AI Comm.'12]

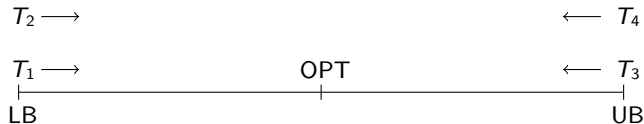
- Splitting approach:
 - Search on different values of the upper bound
- Portfolio approach:
 - Multiple threads perform lower and upper bound search

Parallel MaxSAT (Splitting)

[RCRA'11, AI Comm.'12]



- Local Upper Bound (LUB):
 - Cost between LB and UB
- Splitting approach:
 - 1 thread searches on the LB (T_1)
 - 1 thread searches on the UB (T_2)
 - Remaining threads search on LUB (T_3, T_4)



- Portfolio approach:
 - Half threads search on the LB (T_1, T_2)
 - Half threads search on the UB (T_3, T_4)
 - Diversification of the search using **different** cardinality constraints

Parallel MaxSAT (Experimental Results)

- Benchmarks: 497 industrial partial MaxSAT instances
- Timeout: 1,800 seconds
- Solvers:
 - WBO (sequential MaxSAT solver - 1 run):
 - Uses a linear search algorithm for 10% of the time limit
 - If no solution is found changes to unsatisfiability-based algorithm
 - PWBO (parallel MaxSAT solver - 10 runs):
 - 2 threads, PWBO-T2
 - 4 and 8 threads, PWBO-S (splitting approach)
 - 4 and 8 threads, PWBO-P (portfolio approach)

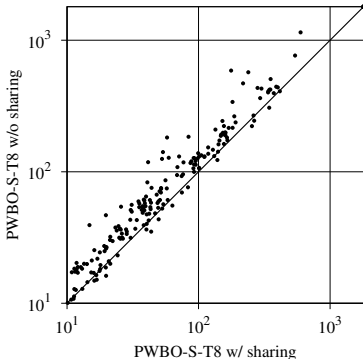
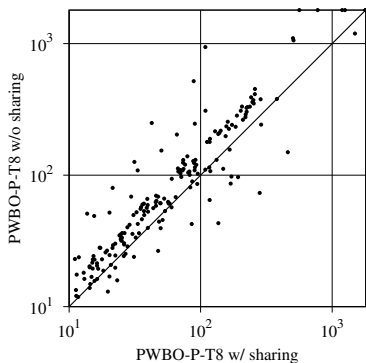
Parallel MaxSAT (Experimental Results)

- Number of instances solved by each solver and speedup of PWBO:

	#Solved	Speedup
WBO	317	1.00
PWBO-T2	398	2.69
PWBO-P-T4	399	3.92
PWBO-S-T4	399	4.16
PWBO-S-T8	399	4.83
PWBO-P-T8	403	5.19

Parallel MaxSAT (Experimental Results)

- Impact of sharing learned clauses:



- PWBO exhibits non-deterministic behavior:
 - Different runs of the solver may find different solutions
- 504 partial industrial benchmarks (10 runs):

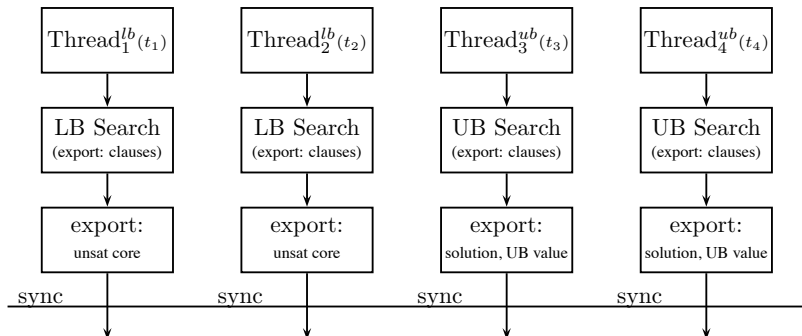
#Solved	Avg. #Models	Avg. Δ run time
405	7.52	20.77%

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#Solved	Avg. #Models	Avg. Δ run time
405	7.52	20.77%

- **Solution:** import information at fixed points during the search

- Deterministic version of PWBO-P:



- The definition of synchronization points must be deterministic:
 - Synchronize after k conflicts (period)

Different kinds of synchronization:

- Standard synchronization:
 - Lower bound search syncs at each core
- Period synchronization:
 - Lower bound search syncs at each period
- Dynamic synchronization:
 - Dynamically adjust the size of the period

Deterministic Parallel MaxSAT (Results)

- Comparison between non-deterministic and deterministic solvers:

Solver	#Solved	Speedup
Non-Deterministic	405	1.00
Standard	400	0.77
Period	400	0.88
Dynamic	401	0.90

- Performance of deterministic solvers are comparable to performance of non-deterministic solver

- Sharing learned clauses improves the performance of the solver
- Not all learned clauses should be shared

- Sharing learned clauses improves the performance of the solver
- Not all learned clauses should be shared
- **Question:** which learned clauses should be shared?

- Static:
 - Learned clauses are shared within a given cutoff
- Dynamic:
 - Dynamic heuristics adjust the cutoff during the search
- Freezing:
 - Shared clauses are frozen until expected to be useful

Clause Sharing Heuristics (Experimental Results)

- Benchmarks: 504 industrial partial MaxSAT instances
- Portfolio version of PWBO with 4 threads:
 - Fair evaluation: dynamic deterministic version of PWBO was used
- Solvers:
 - Static heuristics: LBD 5, Size 8, Size 32
 - Dynamic heuristic: starts with a cutoff of size 8
 - Freezing heuristic: uses a cutoff of size 32

Clause Sharing Heuristics (Experimental Results)

- Comparison between clause sharing heuristics:

	Avg. #Clauses	Avg. Size	#Solved	Speedup
No Sharing	-	-	400	1.00
Random	40,686.10	99.57	400	1.12
LBD 5	20,822.01	12.66	401	1.25
Size 8	16,903.33	5.41	401	1.28
Size 32	48,687.91	13.42	401	1.24
Dynamic	28,496.23	8.57	401	1.38
Freezing	31,827.38	10.93	402	1.37

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 - Linear search algorithms
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- Parallel MaxSAT:
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 - Deterministic approaches
 - Clause sharing heuristics
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- Unsatisfiability-based algorithms are very effective
- Performance is related with unsatisfiable cores given by SAT solver:
 - Some unsatisfiable cores may be unnecessarily large
 - **Solution:** Partitioning of the soft clauses

(1) Partition the soft clauses



- (1) Partition the soft clauses
- (2) Add a new partition to the formula



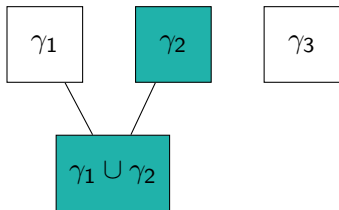
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- (2) Add a new partition to the formula
- (3) While the formula is unsatisfiable:
 - o Relax unsatisfiable core



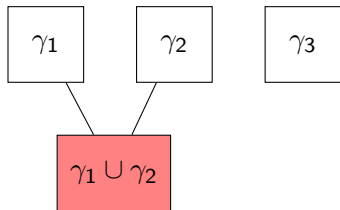
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- (4) The formula is satisfiable:
 - If there are no more partitions:
 - ▷ Optimum found
 - Otherwise, **go back to 2**



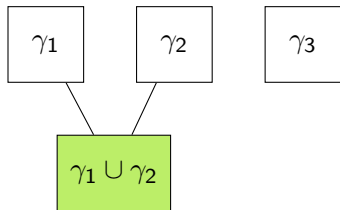
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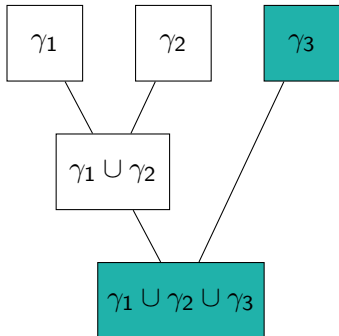
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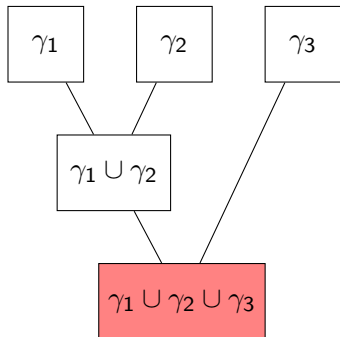
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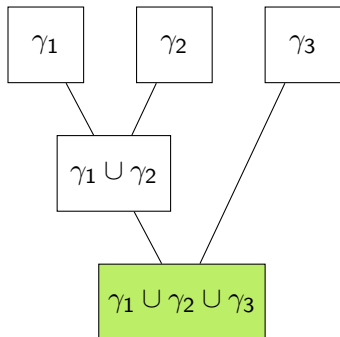
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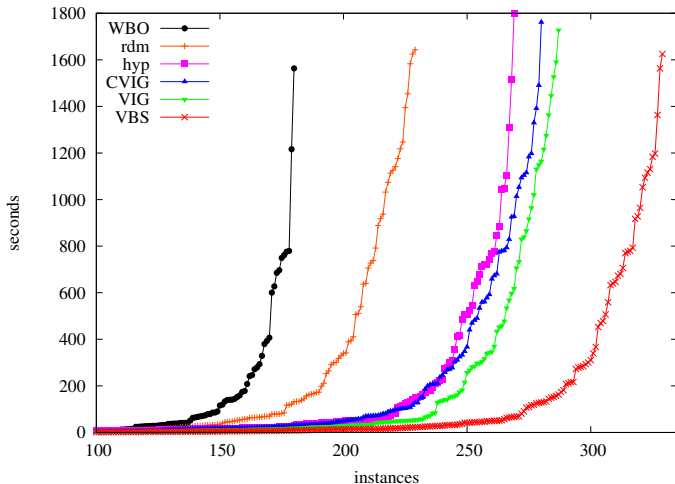
- Weight-based partitioning:
 - Soft clauses with the same weight belong to the same partition
- Graph-based partitioning:
 - Hypergraph graph representation
 - Variable Incidence Graph (VIG) representation
 - Clause-Variable Incidence Graph (CVIG) representation

MaxSAT Partitioning (Results)

- Benchmarks:
 - 504 industrial partial MaxSAT instances
 - 598 weighted partial MaxSAT instances
- Solvers:
 - WBO
 - WEIGHT (Weight-based partitioning)
 - RDM (Random partitioning – 16 partitions)
 - HYP (Hypergraph partitioning – 16 partitions)
 - VIG (Community partitioning – Variable Incidence Graph)
 - CVIG (Community partitioning – Clause-Variable Incidence Graph)
 - VBS (Virtual Best Solver)

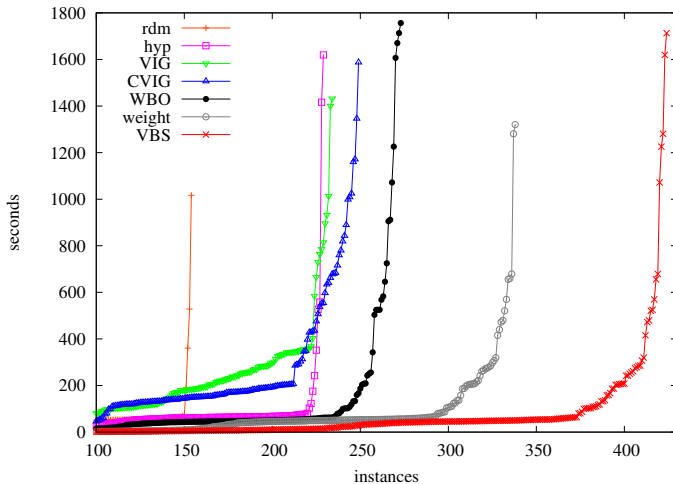
MaxSAT Partitioning (Results)

- Running times of solvers for industrial partial MaxSAT instances



MaxSAT Partitioning (Results)

- Running times of solvers for weighted partial MaxSAT instances



Conclusions

- PWBO first parallel MaxSAT solver for multicore architectures:
 - Winner of several tracks in the MaxSAT evaluations
 - Publicly available: <http://sat.inesc-id.pt/pwbo/>
- Deterministic parallel MaxSAT solvers have comparable performance to non-deterministic
- Sharing learned clauses boost the performance of the solver
- Partitioning-based techniques improves sequential MaxSAT

Publications

- International Journals, Conferences, Workshops:
 - 2013: AI Comm.'13*, SAT'13, RCRA'13
 - 2012: Constraints'12, AI Comm.'12, ECAI'12, LION'12, RCRA'12
 - 2011: ICTAI'11, RCRA'11
 - 2010: SAT'10, ICTAI'10
 - 2009: ModRef'09

* Under review