Experimental Analysis of Backbone Computation Algorithms

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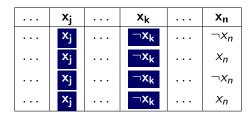
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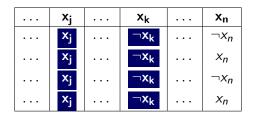


 ×j	 x _k	 Хn
 хj	 $\neg x_k$	 $\neg x_n$

 x _j	 x _k	 x _n
 xj	 $\neg x_k$	 $\neg x_n$
 xj	 $\neg x_k$	 x _n

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$$\phi \models x_j \qquad \phi \models \neg x_k$$

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 - upper bound for number of models

 2^{n-k} , where *n* #variables and *k* #backbones

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\begin{array}{l} \mbox{gas-engine} \lor \mbox{electric-engine} \\ \mbox{electric-engine} \Rightarrow \mbox{automatic} \\ \neg \mbox{automatic} \lor \neg \mbox{manual} \end{array}
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```



- Can we compute backbones for large instances?
- How many backbone literals do real-world instances have?

Armory

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$$SAT(x \land \neg x) = (false, -)$$

Model Enumeration

Input : CNF formula φ **Output**: Backbone of φ , ν_R $\nu_R \leftarrow \{\neg x, x \mid x \in X\}$ // initial backbone estimate repeat $(\mathsf{outc},\nu) \leftarrow \mathsf{SAT}(\varphi)$ // SAT solver call if outc = false then // terminate if unsatisfiable **return** ν_R $\nu_R \leftarrow \nu_R \cap \nu$ // update backbone estimate $\omega_B \leftarrow \text{BlockClause}(\nu)$ // block model $\varphi \leftarrow \varphi \cup \omega_B$ until $\nu_R = \emptyset$ return Ø

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 $\phi \models I$ iff UNSAT $(\phi \land \neg I)$

$$\phi \models x$$

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return ν_R

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• SAT is called twice per variable

// / is backbone

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	x _i		
	$\neg x_i$		
÷	÷	÷	

• if ν is a model of ϕ and $I \in \nu$ then $\neg I$ is not a backbone

• if ν is a model of ϕ and $l \in \nu$ then $\neg l$ is not a backbone

$$\mathbf{x_i}$$
 \dots $\mathbf{x_i}$ $\mathbf{x_i}$ \vdots \vdots

• **OR:** if $I \notin \nu$, for some model ν , then I is not a backbone

Improving Iterative Testing

```
Input : CNF formula \varphi, with variables X
Output: Backbone of \varphi, \nu_R
\Lambda \leftarrow \{x, \neg x \mid x \in X\}
\nu_R \leftarrow \emptyset ///
```

```
foreach I \in \Lambda do
```

```
(\text{outc}, \nu) \leftarrow \text{SAT}(\varphi \cup \{\neg I\})
if \text{outc} = \text{false then}
```

```
 \left[ \begin{array}{c} \nu_R \leftarrow \nu_R \cup \{I\} \\ \varphi \leftarrow \varphi \cup \{I\} \end{array} \right]
```

return ν_R

// candidates for backbone
// initial backbone estimate

// Backbone identified

 model enumeration computes backbone from the upper bound (at the beginning everything can be a backbone)

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idea

• look only for those models that show that something that still can be a backbone, is not a backbone

Upper Bound Algorithm

```
Input : CNF formula \varphi, with variables X
Output: Backbone of \varphi, \nu_R
(outc, \nu_R) \leftarrow SAT(\varphi)
                                                    // initial backbone estimate
if outc = false then return \emptyset
                                                                // unsatisfiable case
while \nu_R \neq \emptyset do
    (\mathsf{outc},\nu) \leftarrow \mathsf{SAT}(\varphi \land \bigvee_{l \in \nu_P} \neg l)
    if outc = false then
         return \nu_R
                                        // estimate contains only backbones
    else
      \ \ \nu_R \leftarrow \nu_R \cap \nu
```

return ν_R

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idea

- split the estimate into chunks of size K
- test only one chunk at a time

Upper Bound Chunking Algorithm

```
Input : CNF formula \varphi, with variables X. K \in \mathbb{N}^+
Output: Backbone of \varphi, \nu_R
(\mathsf{outc}, \Lambda) \leftarrow \mathsf{SAT}(\varphi)
                                                                 // initial backbone estimate
if outc = false then return \emptyset
                                                                                // unsatisfiable case
\nu_R \leftarrow \emptyset
                                                                 // initial backbone estimate
while \Lambda \neq \emptyset do
     k \leftarrow \min(|\nu_R|, K)
     \Gamma \leftarrow \text{pick } k \text{ literals from } \Lambda
     (\text{outc}, \nu) \leftarrow \text{SAT}(\varphi \land \bigvee_{I \in \Gamma} \neg I)
     if outc = false then
        \begin{vmatrix} \nu_R \leftarrow \nu_R \cup \mathsf{\Gamma} \\ \varphi \leftarrow \varphi \land \bigwedge_{I \in \mathsf{\Gamma}} I \end{vmatrix} 
                                                        // chunk contains only backbones
     else
       \land \land \land \land \land \nu
                               // something in the chunk not backbone
```

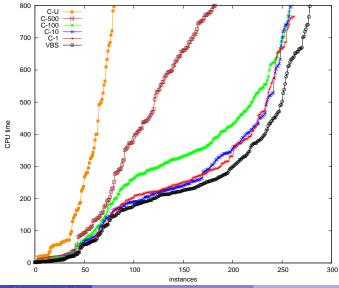
return ν_R

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- K = 1 is the iterative algorithm
- K = |X| is the upper-bound algorithm

Results



Janota et al. (INESC-ID, UCD, IST)

On Computing Backbones

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- chunking overall does not outperform the iterative algorithm but helps in some cases
- adaptive algorithms for chunks