## Experimental Analysis of Backbone Computation Algorithms

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| $\ldots$ | $\mathbf{x}_{\mathbf{j}}$ | $\ldots$ | $\mathbf{x}_{\mathbf{k}}$ | $\ldots$ | $\mathbf{x}_{\mathbf{n}}$ |
| :--- | :---: | :---: | :---: | :---: | :---: |
| $\cdots$ | $x_{j}$ | $\cdots$ | $\neg x_{k}$ | $\cdots$ | $\neg x_{n}$ |
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$$
\phi \models x_{j} \quad \phi \models \neg x_{k}
$$

## Motivation

- backbones tell us more about the formula, e.g.
- upper bound for number of models

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2^{n-k}, \text { where } n \# \text { variables and } k \text { \#backbones }
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- product configuration

$$
\left.\begin{array}{l}
\text { gas-engine } \vee \text { electric-engine } \\
\text { electric-engine } \Rightarrow \text { automatic } \\
\neg \text { automatic } \vee \neg \text { manual }
\end{array}\right\}
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## Motivation

- Can we compute backbones for large instances?
- How many backbone literals do real-world instances have?


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\begin{gathered}
\operatorname{SAT}(x \vee y)=(\text { true },\{x, \neg y\}) \\
\operatorname{SAT}(x \wedge \neg x)=(\text { false },-)
\end{gathered}
$$

## Model Enumeration

Input : CNF formula $\varphi$
Output: Backbone of $\varphi, \nu_{R}$
$\nu_{R} \leftarrow\{\neg x, x \mid x \in X\}$
repeat
(outc, $\nu) \leftarrow \operatorname{SAT}(\varphi)$
if outc $=$ false then return $\nu_{R}$
$\nu_{R} \leftarrow \nu_{R} \cap \nu$
$\omega_{B} \leftarrow \operatorname{BlockClause}(\nu)$
$\varphi \leftarrow \varphi \cup \omega_{B}$
until $\nu_{R}=\emptyset$
return $\emptyset$

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\phi \models x
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## Iterative SAT Testing

- Can we decide whether $I$ is a backbone using a SAT solver?

$$
\begin{array}{llll}
\phi=I & \text { iff } & \text { UNSAT }(\phi \wedge \neg I) \\
\phi=x & \text { iff } & \operatorname{UNSAT}(\phi \wedge \neg x)
\end{array}
$$

## Iterative SAT Testing

Input : CNF formula $\varphi$, with variables $X$
Output: Backbone of $\varphi, \nu_{R}$

```
\nuR}\leftarrow
foreach I G{\negx,x|x\inX} do
    (outc, \nu)\leftarrow\operatorname{SAT}(\varphi\cup{\neg/})
    if outc = false then
        \nu
        \varphi \leftarrow \varphi \cup \{ / \}
return }\mp@subsup{\nu}{R}{
```


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- SAT is called twice per variable


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| $\vdots$ | $\vdots$ | $\vdots$ |

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| $\ldots$ | $\mathbf{x}_{\mathbf{i}}$ | $\ldots$ |  |
| :---: | :---: | :---: | :--- |
| $\ldots$ | $\neg x_{i}$ | $\ldots$ | $\phi \not \models x_{i}$ |
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| $\ldots$ | $\neg x_{i}$ | $\ldots$ |  |
| $\vdots$ | $\vdots$ | $\vdots$ |  |
|  |  |  |  |

- OR: if I $\notin \nu$, for some model $\nu$, then I is not a backbone


## Improving Iterative Testing

Input : CNF formula $\varphi$, with variables $X$
Output: Backbone of $\varphi, \nu_{R}$
$\Lambda \leftarrow\{x, \neg x \mid x \in X\}$
$\nu_{R} \leftarrow \emptyset$
foreach $I \in \Lambda$ do
$($ outc,$\nu) \leftarrow \operatorname{SAT}(\varphi \cup\{\neg /\})$
if outc $=$ false then
else
$\llcorner\Lambda \leftarrow \Lambda \cap \nu$
return $\nu_{R}$
$\varphi \leftarrow \varphi \cup\{I\}$
$\left[\begin{array}{l}\nu_{R} \leftarrow \nu_{R} \cup\{I\} \\ \varphi \leftarrow \varphi \cup\{I\}\end{array}\right.$

$$
\begin{array}{ll}
\nu_{R} \leftarrow \nu_{R} \cup\{/\} & / / \\
\text { Backbone identified }
\end{array}
$$

// candidates for backbone // initial backbone estimate

## Characteristics

- model enumeration computes backbone from the upper bound (at the beginning everything can be a backbone)


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## idea

- look only for those models that show that something that still can be a backbone, is not a backbone


## Upper Bound Algorithm

Input : CNF formula $\varphi$, with variables $X$
Output: Backbone of $\varphi, \nu_{R}$
(outc, $\left.\nu_{R}\right) \leftarrow \operatorname{SAT}(\varphi) \quad / /$ initial backbone estimate if outc $=$ false then return $\emptyset \quad / /$ unsatisfiable case while $\nu_{R} \neq \emptyset$ do
(outc, $\nu) \leftarrow \operatorname{SAT}\left(\varphi \wedge \bigvee_{I \in \nu_{R}} \neg /\right)$
if outc $=$ false then return $\nu_{R}$
// estimate contains only backbones
else
$L \nu_{R} \leftarrow \nu_{R} \cap \nu$
return $\nu_{R}$

## Characteristics

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## idea

- split the estimate into chunks of size $K$
- test only one chunk at a time


## Upper Bound Chunking Algorithm

Input : CNF formula $\varphi$, with variables $X . K \in \mathbb{N}^{+}$
Output: Backbone of $\varphi, \nu_{R}$
(outc, $\Lambda$ ) $\leftarrow \operatorname{SAT}(\varphi)$
if outc $=$ false then return $\emptyset$
$\nu_{R} \leftarrow \emptyset$
while $\Lambda \neq \emptyset$ do
$k \leftarrow \min \left(\left|\nu_{R}\right|, K\right)$
$\Gamma \leftarrow$ pick $k$ literals from $\Lambda$
(outc, $\nu) \leftarrow \operatorname{SAT}\left(\varphi \wedge \bigvee_{I \in \Gamma} \neg /\right)$
if outc $=$ false then
$\nu_{R} \leftarrow \nu_{R} \cup \Gamma \quad / /$ chunk contains only backbones $\varphi \leftarrow \varphi \wedge \bigwedge_{I \in \Gamma} I$
else

$$
\Lambda \leftarrow \Lambda \cap \nu
$$

return $\nu_{R}$

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- $K$ backbones can be shown in one call thus reducing the number of calls


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- $K=1$ is the iterative algorithm
- $K=|X|$ is the upper-bound algorithm


## Results



## Summary and Future Work

- analysis of algorithms for computing backbones that use a SAT solver as a blackbox


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- iterative algorithm (one call per variable)
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- upper bound (backbone proven in the last call)
- generalized by chunking algorithm ( $K$ literals can be shown as a backbone in one call)
- chunking overall does not outperform the iterative algorithm but helps in some cases
- adaptive algorithms for chunks

